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Physics League Across Numerous Countries for Kick-Ass Students

Munich \& online
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## Problems

## Preliminary remarks

Dear participants,
welcome to this year's PLANCKS exercise booklet! Today, it's all about solving (theoretical) physics problems. The highest scoring teams will hold the title of this year's PLANCKS champions. Before solving the problems, please carefully read the following remarks and excerpts from the PLANCKS rules containing important information about the exam:

1. The competition exam lasts four hours. There are ten problems each worth ten points.
2. The exercises are solved independently and without any external help by each team.
3. The teams commit to sticking to the rules, especially to fairness towards other teams in the scientific contest. If a team violates the rules, it will be disqualified.
4. In case the formulation of an exercise is unclear, every participant can request clarifications from the jury in written form by handing the question to the volunteers. The jury then answers the question in written form. If the information is relevant for all teams, the jury will inform every team.
5. The exercises are formulated in English. The solutions need to be handed in in English as well.
6. The jury has the right to change or to withdraw problems during the competition. In such a case, the jury informs every team and adjusts the grading appropriately. There are no further consequences.
7. Usage of hardware which is not approved by the jury is forbidden. Dictionaries and nongraphical calculators are allowed!
8. The organisers make sure in the best way possible that the participating teams have no access to mobile devices during the competition.
9. In exceptional cases, the Organising Committee has the right to stop, to interrupt or to extend the competition or to change the grading.
10. In case of dubiety concerning the rules and standards, the jury decides about those.

Last, please note the following:

- Solutions for different exercises have to be handed in on separate pieces of paper. This means that you should start a new sheet when writing down the solution of a new exercise.
- Unreadable solutions won't be corrected. If there are two solutions for one exercise and no one is crossed out, both will be counted as wrong.
- Please write the name of your team on every sheet of paper you hand in.

If any questions arise during the competition, please ask the assistants on your floor.
We wish you a nice time and lots of success solving the PLANCKS 2022 problems!
The PLANCKS 2022 Jury (Oliver Diekmann, Max Fahn, Miriam Gerharz, Philipp Heinen, Sören Kotlewski, Dr. Charlotta Lorenz, Alexander Osterkorn, Dominik Rattenbacher, Dr. Markus Schmitt, Philippe Suchsland, Rajshree Swarnkar, Dr. Matthias Zimmermann)

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## Problem 1

## On the Gravitational Three-Body Problem

## Prof. Dr. Karl-Henning Rehren - Georg-August-Universität Göttingen

Background One sometimes reads that in gravitating system of $N$ stars, each star "orbits around the common center of mass". This statement is certainly to a large extent true if "around" is meant in a qualitative sense. But of course, the orbit is neither a circle nor a Keplerian ellipse with the center of mass in its focal point, so that the notion "around" cannot be given a sharp meaning. On the other hand, for three stars it is known that there exist very special solutions with the stars in an equilateral triangle position that rigidly rotates around its center of mass (each star orbiting in a circle) - independent of the masses.

We want to study (among other things) whether there is in general a single point $\vec{x}^{*}$ in space such that the total force vectors

$$
\begin{equation*}
\vec{F}_{i}=\sum_{j \neq i} \vec{F}_{i, j} \tag{1.1}
\end{equation*}
$$

of each star point towards that point, and if so, whether this is a special feature of the $1 / r^{2}$-law of the gravitational force. For the sake of this problem, we put Newton's constant $G_{N}=1$ and write the force exerted by star 2 on star 1 as

$$
\begin{equation*}
\vec{F}_{1,2}=-m_{1} m_{2} \frac{\vec{x}_{12}}{\left|\vec{x}_{12}\right|^{n+1}} \quad\left(\vec{x}_{i j}:=\vec{x}_{i}-\vec{x}_{j}\right) . \tag{1.2}
\end{equation*}
$$

To begin with, we put $n=2$ (Newton's Law). It is not difficult to show that for $N \geq 4$ stars, a point $\vec{x}^{*}$ as specified above does not exist in general. (One may just think of systems subdivided into two distant clusters.) So, we consider only $N=3$.
a) [1 point] Recall that the center of mass can be defined as the unique point $\vec{x}_{0}$ such that

$$
\begin{equation*}
\sum_{i=1}^{3} m_{i} \cdot\left(\vec{x}_{i}-\vec{x}_{0}\right)=0 \tag{1.3}
\end{equation*}
$$

For the problem at hand, it is instead useful to define the "center of pseudo-mass" as the unique point $\vec{x}^{*}$ such that

$$
\begin{equation*}
\sum_{i=1}^{3} m_{i}^{*} \cdot\left(\vec{x}_{i}-\vec{x}^{*}\right)=0 \tag{1.4}
\end{equation*}
$$

where the (configuration-dependent) "pseudo-masses" are defined as

$$
\begin{equation*}
m_{i}^{*}:=\left|\vec{x}_{j k}\right|^{3} \cdot m_{i} \tag{1.5}
\end{equation*}
$$

where $j, k=2,3$ if $i=1$ and so on. Solve the equations (1.3) and 1.4 for $\vec{x}_{0}$ and $\vec{x}^{*}$, respectively. Can one expect that $\vec{x}^{*}=\vec{x}_{0}$ in general?
b) [3 points] Show that all total forces $\vec{F}_{i}$ point towards the center of pseudo-mass $\vec{x}^{*}$.

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Hint: Use the result of part a) to show that $\vec{x}_{i}-\vec{x}^{*}$ is a multiple of $\vec{F}_{i}$. It is sufficient to do this for $i=1$.
c) [4 points] Until this point, we have looked at a fixed instant of time. The next question is whether the situation is stable in time, i.e., whether the triangle formed by the three stars can rigidly rotate around the center of pseudo-mass. By the centrifugal law, this would require that

$$
\begin{equation*}
\vec{F}_{i}=-m_{i} \omega^{2} \cdot\left(\vec{x}_{i}-\vec{x}^{*}\right) \tag{1.6}
\end{equation*}
$$

with a common $\omega^{2}$ for all $i=1,2,3$. Analyze this condition (using the result of b) )!
d) [1 point] What changes in parts a) to c) if Newton's $1 / r^{2}$-law 1.2 were replaced by a $1 / r^{n}$-law $(n \neq 0)$, i.e. $\left|\vec{x}_{i j}\right|^{3}$ is replaced by $\left|\vec{x}_{i j}\right|^{n+1}$ in $(1.2)$ and in the definition of the pseudo-mass?
e) [1 point] What changes in parts a) to c) if $n=-1$, i.e., Newton's law (1.2) becomes the elastic force $\vec{F}_{1,2}=-m_{1} m_{2} \vec{x}_{1,2}$ proportional to the product of masses?

## Problem 2

## James Bond's Car Crash in Casino Royale

Dr. Charlotta Lorenz, Dr. Sophie-Charlotte August, Prof. Dr. Sarah Köster - U Göttingen

Background Prof. Dr. Metin Tolan, physicist and president of the University of Göttingen, analyzes in his book Shaken, not stirred - James Bond in the spotlight of physics a scene from the James Bond movie Casino Royale: James Bond is chasing the villain Le Chiffre in a car. Suddenly, Vesper Lynd, Bond's girlfriend, is tied up on the road and Bond jerks the steering wheel to the left, whereupon the car overturns. The following figure shows single frames from the scene in which the car overturns. In the following task, we want to analyze whether the car can actually roll over under the given circumstances.


The car has a mass $m=1750 \mathrm{~kg}$, is $b=1.90 \mathrm{~m}$ wide and $h=1.28 \mathrm{~m}$ high. It drives with a speed $v=128 \mathrm{~km} / \mathrm{h}$ in the gravitational field of the earth with $g=9.81 \mathrm{~m} / \mathrm{s}^{2}$.
a) [1 point] Model the car as a cuboid with a center of mass located centrally at the lower third of the car. Sketch the cross-section of the car with all the forces acting on it when the steering wheel is jerked around. Draw the point about which the car rotates when it rolls over sideways. We are only considering rotation along the longitudinal axis of the car in this task.
b) $[1$ point $]$ Calculate the forces and torques acting on the car.
c) [0.5 points] Think about what has to happen for the car to start rolling over instead of just driving a turn.
d) [1 point] What is the minimum radius of the curve that the car must have before it starts to roll over?
e) $[0.5$ points $]$ In the film, the curve radius is about 200 m , so the car should not roll over by itself. What must happen at a constant curve radius to allow the car to roll over anyway?
f) [0.5 points] When the scene was shot, two additional measures were taken to make the car roll over. One additional device was a $L=2.5 \mathrm{~m}$ long ramp, rising from 0 cm to $H=10 \mathrm{~cm}$, over which the left side of the car drove (that is, the car goes up the ramp with its left wheels). The following figure is a simplified representation of the situation. Sketch the car on the ramp from the rear view, and draw the centrifugal force and gravity with their point of application.
g) [1 point] Calculate the change in angular velocity ( $\dot{\phi}$, see figure (b), where $\phi$ is drawn) of the car caused by the ramp. Consider how long the car needs to drive over the ramp. For simplicity, assume

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Parameters in this sketch are not to scale!
The ramp and the angle $\phi$ are drawn much larger for clarification than they actually are.
that the height of the ramp can be neglected compared to its length. Then calculate the change in angle of the left side of the car compared to the right side. Use small angle approximation.
h) [ 0.5 points] What does the change in angular velocity mean for angular momentum and torque of the car? Describe the torque as a function of the car's moment of inertia $I$ and angular acceleration.
i) [1 point] Now, to calculate the additional force acting on the left side of the car through the ramp, we must first calculate the moment of inertia of the car with respect to the right tires around which it rotates. Model the car as a cuboid. You do not need to explicitly derive the moment of inertia for a cuboid; you can use the familiar formula. Use Steiner's theorem.
j) [1 point $]$ The torque engages the left side of the vehicle. Show that the factor

$$
b /(c \cos \alpha)
$$

is needed to convert the force from the left side of the vehicle to the center of gravity. $b, c$ and $\alpha$ are shown in the sketch above in (c). Use the lever laws and write the cross product as $\vec{d} \times \vec{f}=|\vec{d}||\vec{f}| \sin \alpha$ with the angle $\alpha$ between the vectors. You can neglect $\phi$ here compared to $\alpha$.
k) [ 1 point ] Explicitly calculate the additional force $F_{R}$ generated by the ramp on the center of gravity. Since the ramp is not very high, we can again assume $\alpha \gg \phi$ and $\alpha=24^{\circ}$.

1) [1 point] This force is not sufficient to make the car turn. The film producers tried it and for some cars it works, but for the car used here it is not sufficient. Thus, as a second measure to make the car overturn, an iron bolt with a mass $m_{B}=20 \mathrm{~kg}$ is accelerated by $\Delta v_{B}=10 \mathrm{~m} / \mathrm{s}$ within $\Delta t_{B}=0.1$ $s$ and launched near the left wheels of the car as sketched in the following figure. Calculate the additional force on the center of mass generated in this way. Note that here you must again apply the laws of leverage as calculated in (j).

Rear view of the car at the end of the ramp:


The ramp together with the iron bolt could finally make the car overturn.

## Problem 3

## Rope around the World

Prof. Dr. David DiVincenzo ${ }^{1}$, Philippe Suchsland ${ }^{2}{ }^{1}{ }^{1}$ Peter Grünberg Institute (PGI-2), Forschungszentrum Jülich, Jülich, Germany, ${ }^{2}$ Max Planck Institute for the Physics of Complex systems, Dresden, Germany

Background A loop of rope goes around the circumference of the earth with radius $R$. The rope is ideal ( $\infty$ stretching modulus, $\infty$ strength, 0 bending modulus, infinitely thin). Its mass density is $\rho(\mathrm{kg} / m)$. Its length is such it can be held distance $a$ above the surface, all the way around. This means that if it is laid straight on the surface, there is a $2 \pi a$ leftover. We assume $a \ll R$ (e.g. $a=1 \mathrm{~m}, R \sim 10^{6} \mathrm{~m}$ ).


Someone grasps the rope at point $P$ and raises it. What is the maximum height $h$ to which it can be raised?
a) [1 point] In a first step, we want to build up some physical intuition. First, introduce the quantity $l$, the length of the rope not resting on earth when the rope is held at height $h$. Justify by dimensional analysis and by analysing the limiting behaviour for $a / R \rightarrow 0$ in the case $a=$ const or $\mathrm{R}=$ const that $h, l$ can be expressed by

$$
\begin{array}{cc}
l=c_{1} a^{1-\alpha} R^{\alpha}+\ldots, & 0<\alpha<1, \\
h=c_{2} a^{1-\beta} R^{\beta}+\ldots, & 0<\beta<1, \tag{3.2}
\end{array}
$$

in the limit $a / R \ll 1$.
b) $[0.5$ points $]$ Show that $l / R \ll 1$ for $a / R \ll 1$.
c) [2.5 points] Calculate the constants $c_{1}, c_{2}, \alpha, \beta$ by calculating $l, h$ in the limit $a / R \ll 1$.

Hint: Except for $l / R \ll 1$ this task does not rely on the previous ones.
We now calculate tensions. Suppose the rope is raised to height $\tilde{h}, \pi a<\tilde{h} \ll h$. The rope will look something like this (not to scale):


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Cable theory shows that $y(x)$, a so-called "catenary curve", is a segment of hyperbolic-cosine curves in the limit of uniform gravitational field. We aim to find the differential equations determining the curves $y(x)$. For that, consider the forces acting on the rope. We work in the limit of $a / R \rightarrow \infty$ so you may ignore the curvature of the earth and variations in the gravitational force in all following subtasks.
d) [2 points] Derive, but do not solve, a set of three differential equations determining the three unknown functions $y(x), F_{\mathrm{R}, x}$ and $F_{\mathrm{R}, y}$, where $F_{\mathrm{R}, x}$ and $F_{\mathrm{R}, y}$ are the two vector components of the tension of the rope $\vec{F}_{\mathrm{R}}$. You are free to choose the reference system and express the strength and direction of the gravitational force as $\vec{g}$.

Hint: Consider the forces acting on a short section of the rope.
e) [1.5 points] By introducing the points $G$, where the rope begins to rest on the ground, write down the boundary conditions for the differential equations derived in the previous task, i.e., the conditions needed to fully determine the slope. Particularly, what is the force law that determines the condition at the grounding points $G$ ?
f) [1 point $]$ Solve the set of differential equations.

Hint: You might find the solution of the integral

$$
\begin{equation*}
\int \mathrm{d} z \frac{1}{\sqrt{1+z^{2}}}=\operatorname{asinh}(z)+c, \tag{3.3}
\end{equation*}
$$

where $\operatorname{asinh}(z)$ is the inverse function of $\sinh (z)$, useful.
The solution of the differential equation takes the form $y(x)=a+\cosh (b(x-c)) / b$, which you can use in the following.
g) [1 point] We raise P much higher, but still much lower than the maximum; in particular $\tilde{h}=h / 10$. What is the tension of the rope at point $P$ ?

Hint: You may assume $\left|y^{\prime}\right| \ll 1$ at point $P$.
h) [0.5 points] Based on the result of the previous exercise and $h$ from part c), what will happen with the rope if we raise a real rope in the limit $R \rightarrow \infty$ to height $\tilde{h}=h / 10$ ?

## Problem 4

## The Galactic Centre Laboratory

## Dr. Odele Straub - ORIGINS Excellence Cluster and Max Planck Institute for Extraterrestrial Physics

Background The Milky Way, our home galaxy, is the second largest galaxy (after Andromeda) in the local neighbourhood; it spans about $30 \mathrm{kpc}\left(1 \mathrm{kpc}=1000 \mathrm{pc}=3.1 \times 10^{19} \mathrm{~m}\right)$ in diameter. Deep in its centre resides the supermassive, compact radio source, Sagittarius A* (Sgr A*). While most bright and young stars in the Milky Way are located in the gas rich spiral arms of the galactic disc, the overall star count increases towards the centre. In particular in the innermost 0.04 pc there is a dense cluster of about 100 young and fast moving stars called the S-stars. Their orbits around the central gravitating mass have random orientations. This central region cannot be observed at optical wavelengths due to the thick molecular clouds in our line of sight. However, in the infrared it is possible to pierce through the dust. GRAVITY is a beam-combiner instrument that links the four 8-meter infrared telescopes of the Very Large Telescope (VLT) in Chile into one giant telescope with a diameter of $D=130 \mathrm{~m}$. With its high angular resolution, GRAVITY can monitor extremely faint and distant objects, like the stars in the immediate vicinity of Sgr A*, with a precision that allows to record daily changes in their motion. Consequently, the Galactic centre region has now become a new "laboratory" to probe and test general relativity.

Useful constants: the gravitational constant, $\mathrm{G}=6.7 \times 10^{-11} \mathrm{~m}^{3} / \mathrm{kg} \mathrm{s}^{2}$, the speed of light in vacuum, $\mathrm{c}=3 \times 10^{8} \mathrm{~m} / \mathrm{s}$.
a) [2 points] Mass of the Milky Way: The Sun with its mass of $M_{\odot}=1.99 \times 10^{30} \mathrm{~kg}$ is an average star. It sits at the edge of a spiral arm of the Milky Way and orbits Sgr A* at a distance of $r_{0}=8.28 \mathrm{kpc}$ with a circular velocity of $v_{\odot}=251.05 \mathrm{~km} / \mathrm{s}$.
(i) Estimate the mass of the Milky Way in units of solar masses.
(ii) Explain why this is only a lower limit.

The actual stellar content can be derived from luminosity measurements and amounts to roughly $15 \%$ of the total mass of the Milky Way.
(iii) Where and/or what is the rest?
b) [2 points] Mass of Sgr A* : Astronomers deduce the mass of Sgr A* from the motion of the Sstars. The star S2 (see Fig. 4.1) is particularly well suited due to its short orbital period of $P=16.05$ years, small semi-major axis of $a=0.125 "$ (arcseconds) and high eccentricity $e=0.88$. Its closest approach to the central gravitating mass, i.e. its pericentre is $r_{\text {peri }}=14 \mathrm{mas}$ (milli-arcseconds). First convert the angular size of the orbit from arcseconds to SI units with the help of the Sun's distance from Sgr A*. Then calculate the mass of Sgr A* in units of solar masses.
c) [2 points] Size of Sgr A* : A black hole (BH) is a mathematical object native to a theory of gravity. It is defined by having a horizon instead of a surface, i.e. a critical radius from where not even light can escape.
(i) Derive the critical radius from Newtonian principles. The resulting formula is also found in the theory of General Relativity (GR) and called Schwarzschild radius, $r_{S}$.

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Right Ascension difference from 17 h 45 m 40.045 s


Figure 4.1 Orbits of some of the inner S-stars around Sgr A*, the supermassive compact object in the centre of the Milky Way. The star S2 (red) is due to its short and highly eccentric orbit the most interesting probe of the gravitational field of Sgr A*. At the bottom right, for comparison, some orbits of Solar System bodies. Figure credit: Eisenhauer et al. (2005)
(ii) Calculate $r_{S}$ of $\operatorname{Sgr} \mathrm{A}^{*}$ for the mass you determined above and compare it to Neptune's mean distance from the Sun, $r_{\text {Neptune }}=4.5$ billion km .

The GRAVITY/VLT instrument not only sees the stars near Sgr A* but also detects flickering light from a location even closer. This light originates from occasional hot plasma flares. They loop around Sgr A* with an average radius of $60 \mu$ as (micro-arcseconds).
(iii) Argue, considering theory and observations, why Sgr A* must be a compact object and is likely to be a BH.
d) [1 point] GRAVITY Instrument: The perhaps most important equation in (observational) astronomy gives the angular resolution $R$ of any telescope in units of radians for any given wavelength
$\lambda$ and telescope diameter $D$

$$
\begin{equation*}
R=1.22 \frac{\lambda}{D}, \tag{4.1}
\end{equation*}
$$

GRAVITY/VLT observes at infrared wavelengths of $2.2 \mu \mathrm{~m}$. What is its resolution? Estimate the diameter of an infrared telescope needed to resolve the black hole horizon. Where would you build it?
e) [1 point] Gravitational Redshift: There are three classical tests of GR proposed by Albert Einstein: the perihelion precession of planet Mercury, the deflection of light by the Sun, and the gravitational redshift of light. To detect the effect of gravitational redshift in the galactic centre, one follows the star S2 on its orbit. Astronomers not only track its positions (with GRAVITY) but also record the radial velocities using a spectrometer (e.g. SINFONI, or ERIS at the VLT). The stellar spectrum shows a prominent absorption line at a wavelength $\lambda^{\prime}$. Explain what gravitational redshift is and how it is related to the star's velocity. Where do you expect the strongest effect during the orbit of S2?
f) [2 points] Precession of the Pericentre: Recently, astronomers showed that the star S2 precesses around $\mathrm{Sgr} \mathrm{A}^{*}$. That is to say, S 2 is not moving on a closed ellipse, but on an open rosette-like trajectory. With this finding GR passed another test in the Galactic centre. S2 currently approaches the apocentre of its orbit, i.e. the farthest point from Sgr A*. Observations indicate that the pericentre of S2 advances each orbit by a small angle, $\delta \varphi=12^{\prime} /$ orbit. Calculate by how much the position of the apocentre changes (in mas). Can GRAVITY resolve this? Note: with the help of adaptive optics the exposure time on a target star can be prolonged so that the actual resolution is about ten times better than the nominal R-value you calculated above.

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## Problem 5

## Conditions for a Self-Heated Fusion Plasma

Prof. Dr. Sibylle Günter - Max Planck Institute for Plasma Physics, Garching bei München, Germany

Background In a fusion power plant, energy shall be released by the fusion reaction of a deuterium and a tritium nuclei to an $\alpha$ particle and a neutron:

$$
\begin{equation*}
\mathrm{D}+\mathrm{T} \rightarrow{ }^{4} \mathrm{He}+n+17.5 \mathrm{MeV} . \tag{5.1}
\end{equation*}
$$

To overcome the Coulomb barrier, the reactants need a sufficient kinetic energy. The number of Coulomb collisions is however always larger than the number of fusion reactions. Therefore, a positive energy balance can only be achieved in a thermal plasma. The D-T reaction has the highest fusion rate compared to any other reaction, at lowest plasma temperature. Nevertheless, a plasma temperature of about 10 keV is required. In a future reactor, the plasma should be heated by the energy released in the fusion reactions. The neutrons leave the plasma nearly without interactions, and thus only the $\alpha$ particles contribute to plasma heating. The heat (=energy) transport of a magnetically confined fusion plasma is determined by several effects, of particular importance are radiation (mostly bremsstrahlung) and turbulent transport. To characterize the energy losses, often the so-called energy confinement time $\tau_{E}$ is used, a measure that corresponds to the time after which the plasma is significantly cooled down (after heating is switched off).
a) [2 points] Calculate how the total energy of 17.5 MeV is divided between ${ }^{4} \mathrm{He}$ and the neutron in the centre of mass frame of the fusing particles.

Hint: Use momentum and energy balance.
b) [2 points] Calculate the heating power $P_{\text {heat }}$ due to the $\alpha$ particles for a fusion power plant (volume: $V=1000 \mathrm{~m}^{3}$ ) with a constant electron density of $n_{e}=10^{20} \mathrm{~m}^{-3}$. Assume that the plasma consists of $50 \% \mathrm{D}$ and $50 \% \mathrm{~T}$ ions and the electrons. Keep in mind that the plasma is always (quasi-)neutral, i.e. the number of electrons balances the number of ions. For a thermal plasma, the reactivity (number of fusion reactions per volume per time) is approximately given by $\langle\sigma v\rangle \approx 10^{-22} \mathrm{~m}^{3} \mathrm{~s}^{-1}$ for $T=10 \mathrm{keV}$.
c) [2 points] Provide an expression for the loss power. The loss power $P_{\text {loss }}$ is defined by the thermal energy of the plasma devided by the energy confinement time $\tau_{E}$. Assume that the plasma behaves like an ideal gas.
d) [2 points] Balance plasma heating and loss power to derive the so-called Lawson criterion, a criterion in terms of plasma density $n=n_{i}$, i.e. equal to the ion density, temperature $T$ and energy confinement time $\tau_{E}$. Please note: In the temperature range considered $(\approx 10 \mathrm{keV})$ the fusion reactivity increases with temperature approximately proportional to $T^{2}$.
e) [2 points] As the fusion reactions produce ${ }^{4} \mathrm{He}$, it is not consistent to assume that the plasma consists of D and T only. By how much would the fusion power be reduced as compared to a pure D-T plasma if $10 \%$ of the plasma ions would be ${ }^{4} \mathrm{He}$ ?

## Problem 6

## Boltzmann-Factors from Information Entropy

Prof. Dr. Björn Malte Schäfer - Fakultät für Physik und Astronomie, Heidelberg University, Germany

Background Statistical mechanics operates under the assumption (called the fundamental postulate) that in thermal equilibrium all states at a given energy are equally likely (defining the microcanonical ensemble) and if energy can fluctuate, states with energy difference $\Delta \epsilon$ are populated according to the Boltzmann factor,

$$
\begin{equation*}
p(\Delta \epsilon)=\exp \left(-\frac{\Delta \epsilon}{k_{B} T}\right) \tag{6.1}
\end{equation*}
$$

$T$ being the temperature and $k_{B}$ the Boltzmann-constant. There is a more fundamental idea though: Claude Shannon has shown that the information entropy $S$

$$
\begin{equation*}
S=-\int \mathrm{d} x p(x) \ln p(x)=-\langle\ln p\rangle \tag{6.2}
\end{equation*}
$$

is a positive measure of randomness of a distribution $p(x)$ and is additive for independent random processes. There are also alternatives, for instance the entropy measure,

$$
\begin{equation*}
S_{\alpha}=\frac{1}{1-\alpha} \ln \int \mathrm{d} x p^{\alpha}(x)=-\frac{1}{\alpha-1} \ln \left\langle p^{\alpha-1}\right\rangle \tag{6.3}
\end{equation*}
$$

with a free positive parameter $\alpha \neq 1$ proposed by Alfred Rényi.
One could now try to reason like this: $(i)$ thermal equilibrium should correspond to the state of highest randomness, and as (ii) information entropy is such a measure of randomness, the distribution of systems of an ensemble in thermal equilibrium should realize the highest information entropy.

Information entropies $S$ and $S_{\alpha}$ are functionals for the actual distribution $p(x) \mathrm{d} x, x$ being the collection of phase space coordinates, and therefore one can carry out functional variations and find the corresponding distributions: We shall try this for Shannon's entropy as well as for Rényi's entropy!
a) [2 points] Let's get ready with entropies.

Please compute the entropy $S$ for a Gaussian distribution

$$
\begin{equation*}
p(x)=\frac{1}{\sqrt{2 \pi \sigma^{2}}} \exp \left(-\frac{x^{2}}{2 \sigma^{2}}\right) \tag{6.4}
\end{equation*}
$$

as a function of $\sigma^{2}$. What is the Shannon-entropy $S$ for a step distribution

$$
p(x)=\left\{\begin{array}{ll}
\frac{1}{b-c} & \text { if } c<x<b  \tag{6.5}\\
0 & \text { else }
\end{array},\right.
$$

does the entropy increase if the interval or the variance become larger? What is the physical interpretation of this? Now, try out the Rényi-entropy for both distributions: Do they scale in a similar way with $\sigma^{2}$ or $b-a$ ?

Hint: The relation $\int \mathrm{d} x e^{-x^{2}}=\sqrt{\pi}$ might be useful.

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b) [2 points] Micro- and canonical ensembles from Shannon's entropy

The constant distribution for the microcanonical ensemble is derived like this: One determines the distribution that maximises $S$ under the boundary condition $\int \mathrm{d} x p(x)=1$. This leads to the following variation

$$
\begin{equation*}
\delta\left[S(p)+\lambda\left(\int \mathrm{d} x p(x)-1\right)\right]=-\delta \int \mathrm{d} x p(x) \ln p(x)+\lambda \delta\left(\int \mathrm{d} x p(x)-1\right)=0 \tag{6.6}
\end{equation*}
$$

with a Lagrange-multiplier $\lambda$. The solution is $p(x)=e^{(\lambda-1)}=$ const, where $\lambda$ can in principle be determined from $\int \mathrm{d} x p(x)=1$. A constant distribution maximises therefore $S$, and the constant distribution of systems across phase space $x$ would already be the microcanonical ensemble! Please solve equation 6.6) and confirm that $p(x)=e^{(\lambda-1)}=$ const is a solution.

Let's try out to get the Boltzmann-factor: Please derive the distribution $p(x)$ that maximises $S$ with the additional boundary condition $\int \mathrm{d} x p(x) \epsilon(x)=\epsilon$ (imposed with a second Lagrangemultiplier $\mu$ ), here $\epsilon(x)$ is a function which returns the energy for given system-coordinates $x$, the exact form of this function is irrelevant for the exercise. Furthermore, show that

$$
\begin{equation*}
\frac{p\left(\epsilon\left(x_{2}\right)\right)}{p\left(\epsilon\left(x_{1}\right)\right)}=\exp \left(\mu \cdot\left(\epsilon\left(x_{2}\right)-\epsilon\left(x_{1}\right)\right)\right) \tag{6.7}
\end{equation*}
$$

at fixed $x$, which has already the shape of a Boltzmann-factor. Please show by using the definition of temperature $T$ in the microcanonical ensemble,

$$
\begin{equation*}
\frac{\partial S}{\partial \epsilon}=\frac{1}{k_{B} T} \tag{6.8}
\end{equation*}
$$

that the Lagrange-multiplier needs to be $\mu=-1 /\left(k_{B} T\right)$.
Hint: Here is a short recap on variational calculus: You may view the entropy $S$ as a functional, mapping a function $p: \mathbb{R} \rightarrow \mathbb{R}$ to a real value $S(p)=-\int \mathrm{d} x p(x) \ln p(x)$. For such a functional, the first variation is given by $\delta S(p)=\left.\frac{\partial}{\partial \epsilon} S(p+\epsilon h)\right|_{\epsilon=0}$, where $h$ is another function from the same vector space as $p$. If the first variation of $S$ around $p$ equals 0 , you know that p maximizes or minimizes $S$. The same method can also be used with boundary conditions by adding them via constant Lagrange-multipliers, as shown in equation (6.6).
For this task, you don't have to determine the exact value of the Lagrange-multiplier $\lambda$.
c) [2 points] Micro- and canonical ensembles from Rényi's entropy

Show that the constant distribution maximises the Rényi entropy $S_{\alpha}$, which would correspond to the microcanonical ensemble. Generalising this result with a constraint on energy, can you derive the ratio $\frac{p\left(\epsilon\left(x_{2}\right)\right)}{p\left(\epsilon\left(x_{1}\right)\right)}$ ? What needs to hold for $\epsilon\left(x_{2}\right)-\epsilon\left(x_{1}\right)$, such that you can approximate the result to a similar form as the result for the Shannon entropy. At last derive the Boltzmann-factor $\mu$ from the maximised Rényi entropy and $\frac{\partial S}{\partial \epsilon}=\frac{1}{k_{B} T}$ (without any approximations).

Hint: Again, the actual value of the Lagrange-multiplier $\lambda$ does not matter.

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d) [2 points] Equivalence of Shannon and Rényi-entropies

Please show that in the limit $\alpha \rightarrow 1$ one recovers Shannon's entropy measure from the Rényientropy,

$$
\begin{equation*}
\lim _{\alpha \rightarrow 1} S_{\alpha}=S \tag{6.9}
\end{equation*}
$$

Hint: Use de l'Hôpital's rule.
e) [2 points] Choice of Shannon's entropy

The familiar Boltzmann-factor comes out if one chooses Shannon's entropy as a measure of randomness, and Rényi's entropy would not reproduce it: What is it in the mathematical formulation about the Rényi-entropy that makes it contradictory to physical observations?

Hint: That's a tough question and there are different strategies to answer it. Maybe think about the case of multidimensional system and conditional probabilities. Alternatively it might help to argue with the scaling of a physical law in mind.

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## Problem 7

## Active Brownian Particle

## Prof. Dr. Michael Schmiedeberg - Institut für Theoretische Physik 1, Friedrich-Alexander-Universität Erlangen-Nürnberg (FAU), Erlangen, Germany

Background Self-propelled particles, also known as active particles, are popular as a model system for an intrinsically non-equilibrium system in statistical physics. Furthermore, they are used to mimic biological or socio-economic systems like colonies of swimming bacteria, fish schools, animal flocks, swarms of birds or insects, or crowds of humans.

In this exercise we consider the motion of a single active particle in a viscous environment in two dimensions. To be specific, we consider a polar point particle at position $\vec{r}(t)$ that points into a direction given by a unit vector $\hat{u}(t)=(\cos \varphi(t), \sin \varphi(t))$ where the angle $\varphi(t)$ is given with respect to some arbitrary reference direction. The particle is subject to Brownian motion due to its surrounding. The activity is given by a force that acts along the direction of the particle, i.e., $\vec{F}_{a}(t)=f_{a} \hat{u}(t)$ with a constant amplitude $f_{a}$.

Due to the temperature, thermal forces $\vec{F}_{T}(t)$ and torques $T_{T}(t)$ act on the particle (details are specified later). Note that only rotations in the plane are considered, i.e., if considered as vectors all quantities related to rotations are perpendicular to the plane of motion.

Any motion of the particle is retarded by a friction force and torque given by Stokes' law and can be assumed to be $\vec{F}_{S}(t)=-\gamma \dot{\vec{r}}(t)$ and $T_{S}=-\gamma_{R} \dot{\varphi}(t)$ with friction constants $\gamma$ and $\gamma_{R}$.

The mass of the particle is $m$ and the moment of inertia is $I$.
a) [1 point] Write down the equations of motion for the position $\vec{r}(t)$ and angle $\varphi(t)$ given the forces and torques specified above.
b) [2 points] Without thermal forces or torques (this includes $T_{S}(0)=-\gamma_{R} \dot{\varphi}(0)=0$ ), calculate the velocity $\dot{\vec{r}}(t)$ of the particle if the initial velocity is $\dot{\vec{r}}(t=0)=v_{0} \hat{u}_{0}$ and the initial direction $\hat{u}(t=0)=\hat{u}_{0}$. Explain your result phenomenologically.
c) [1 point] Determine conditions for the time $t$ depending on the constants mentioned above such that the equations of motions from Task a) can be approximated by

$$
\begin{aligned}
\gamma \dot{\vec{r}}(t) & =f_{a} \hat{u}(t)+\vec{F}_{T}(t), \\
\gamma_{R} \dot{\varphi}(t) & =T_{T}(t) .
\end{aligned}
$$

Motivate your choice for the conditions. A strict calculation is not required. This is called the overdamped limit and will be used for the following tasks.
d) [2 points] Consider the overdamped equations given in Task (c). The thermal force and torque are considered to be random (corresponding to random Brownian kicks from the surrounding). If
averaged over many runs one finds

$$
\begin{aligned}
\left\langle\vec{F}_{T}(t)\right\rangle & =\overrightarrow{0}, \\
\left\langle T_{T}(t)\right\rangle & =0, \\
\left\langle F_{T, j}(t) F_{T, k}\left(t^{\prime}\right)\right\rangle & =2 \gamma k_{B} T \delta_{j k} \delta\left(t-t^{\prime}\right), \\
\left\langle T_{T}(t) T_{T}\left(t^{\prime}\right)\right\rangle & =2 \gamma_{R} k_{B} T \delta\left(t-t^{\prime}\right),
\end{aligned}
$$

where $k_{B} T$ corresponds to the thermal energy of the surrounding and $j, k$ in the third line indicate the spatial component of the thermal forces.
Calculate $\langle\varphi(t)\rangle$ and $\left\langle\varphi^{2}(t)\right\rangle$ in case $\varphi(t=0)=0$ and $\dot{\varphi}(t=0)=0$.
e) [4 points] Consider that the system at $t=0$ has relaxed into a state, where it is properly described by the overdamped equations given in Task (c). Calculate the mean positions $\langle\vec{r}(t)\rangle$ and meansquared displacement $\left.\left.\langle | \vec{r}(t)\right|^{2}\right\rangle$ for small times $t \ll 1$, i.e., up until terms with $t^{2}$, in case $\vec{r}(t=0)=\overrightarrow{0}$, $\dot{\vec{r}}(t=0)=f_{a} \hat{u}_{0} / \gamma, \varphi(t=0)=0$, and $\dot{\varphi}(t=0)=0$.
Discuss the typical distance that a particle travels before it changes its direction significantly. For that consider first the time $t_{\text {reverse }}$ it takes before the velocity changes from the initial condition $\dot{\vec{r}}(t=0)=f_{a} \hat{u}_{0} / \gamma$ to $\dot{\vec{r}}\left(t=t_{\text {reverse }}\right)=-f_{a} \hat{u}_{0} / \gamma$. Note that the time scale related to this typical distance can be seen as the limit of validity of the small-time approximation used here.

Hint: First calculate $\langle\hat{u}(t)\rangle$ (up to first order in t required) and $\left\langle\hat{u}(t) \hat{u}\left(t^{\prime}\right)\right\rangle$ (only zeroth order int required).

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## Problem 8

## Quantum Convolutional Neural Network

Dr. Petr Zapletal, Timo Eckstein, and Prof. Dr. Michael J. Hartmann - Friedrich-Alexander-Universität Erlangen-Nürnberg (FAU)

Background Convolutional neural networks are artificial neural networks, which can be exploited for image recognition. They can process rasterized images and classify whether, for example, a cat or a dog is depicted in a particular image. Quantum convolutional neural networks (QCNNs) are analogous to their classical counterparts and they are designed to recognize quantum phases of matter, which are characterized by long-range quantum correlations. QCNNs process quantum states in order to determine whether they belong to a given quantum phase. Here we consider a minimal example of a QCNN, which processes a quantum state of four qubits. The Hilbert space of each qubit is spanned by two quantum states $|0\rangle_{i}$ and $|1\rangle_{i}$ for $i=1,2,3,4$. The QCNN is based on a quantum circuit depicted in Fig. [8.1, which consists of a convolutional (C) layer, a pooling (P) layer and the measurement of qubits 1 and 4 at the end of the circuit. In the C layer, a translationally invariant unitary transformation $U_{C}$ consisting of CZ gates between neighboring qubits is performed. In the P layer, a unitary transformation $U_{P}$ consisting of two CNOT gates is performed and qubit 2 as well as 3 are discarded such that only qubits 1 and 4 are measured at the end of the circuit.


Figure 8.1 Quantum convolutional neural network consisting of the convolutional layer $U_{\mathrm{C}}$, the pooling layer $U_{\mathrm{P}}$ and the measurement of qubits 1 and 4 . Horizontal lines represent qubits, which are evolved in the circuit from left to right. CZ gates are depicted as vertical lines acting on two qubits denoted by dots. CNOT gates are depicted as vertical lines with a control qubit denoted by a dot and a target qubit denoted by a cross.
$\mathrm{ACNOT}_{i j}$ gate with a control qubit $i$ and a target qubit $j$ performs a bit flip $|0\rangle_{j} \leftrightarrow|1\rangle_{j}$ on the target qubit if the control qubit is in the state $|1\rangle_{i}$ and it does not perform any transformation if the control qubit is in the state $|0\rangle_{i}$. $\mathrm{ACZ}_{i j}$ gate acting on qubits $i$ and $j$ induces a phase shift $|11\rangle_{i j} \rightarrow-|11\rangle_{i j}$ if the two qubits are in the state $|11\rangle_{i j}$ and it does not perform any transformation otherwise, where we use the notation $|\psi \theta\rangle_{i j}=|\psi\rangle_{i} \otimes|\theta\rangle_{j}$ for the tensor product of two states.

The QCNN is designed to recognize the ( $\mathbb{Z}_{2} \times \mathbb{Z}_{2}$ ) symmetry-protected topological (SPT) phase. The states belonging to this quantum phase are characterized by a non-vanishing expectation value of so-called string order parameters. For the four-qubit system considered here, the string order parameters are $\mathcal{O}_{1}=X_{1} X_{3} Z_{4}$ and $\mathcal{\Theta}_{2}=Z_{1} X_{2} X_{4}$. For an input state $|\psi\rangle$, the QCNN output $x_{\mathrm{QCNN}}=\langle\psi| U^{\dagger} \frac{X_{1}+X_{4}}{2} U|\psi\rangle$ is the expectation value of $\left(X_{1}+X_{4}\right) / 2$ measured after the QCNN circuit $U=U_{P} U_{C}$. Hence, the QCNN output corresponds to the expectation value $\langle\psi| \mathcal{O}|\psi\rangle$ of the observable $\mathcal{G}=U^{\dagger} \frac{X_{1}+X_{4}}{2} U$ measured directly on the input state $|\psi\rangle$.
a) [2 points] Prove the following gate identities

$$
\begin{align*}
Z_{i}^{\dagger} X_{i} Z_{i} & =-X_{i},  \tag{8.1}\\
{\left[\mathrm{CZ}_{i j}, Z_{i}\right] } & =\left[\mathrm{CZ}_{i j}, Z_{j}\right]=0,  \tag{8.2}\\
\mathrm{CZ}_{i j}^{\dagger} X_{i} \mathrm{CZ}_{i j} & =X_{i} Z_{j},  \tag{8.3}\\
\mathrm{CZ}_{i j}^{\dagger} X_{j} \mathrm{CZ}_{i j} & =Z_{i} X_{j},  \tag{8.4}\\
\mathrm{CNOT}_{i j}^{\dagger} X_{i} \mathrm{CNOT}_{i j} & =X_{i} X_{j}, \tag{8.5}
\end{align*}
$$

where $X_{i}$ and $Z_{i}$ are Pauli operators with eigenstates $| \pm\rangle_{i}=\left(|0\rangle_{i} \pm|1\rangle_{i}\right) / \sqrt{2}$ and $|0 / 1\rangle_{i}$, respectively, and $[A, B]=A B-B A$ is the commutator.
Hint: use the matrix representation of the quantum states

$$
\left[\begin{array}{l}
1  \tag{8.6}\\
0 \\
0 \\
0
\end{array}\right] \leftrightarrow|00\rangle, \quad\left[\begin{array}{l}
0 \\
1 \\
0 \\
0
\end{array}\right] \leftrightarrow|01\rangle, \quad\left[\begin{array}{l}
0 \\
0 \\
1 \\
0
\end{array}\right] \leftrightarrow|10\rangle,\left[\begin{array}{l}
0 \\
0 \\
0 \\
1
\end{array}\right] \leftrightarrow|11\rangle,
$$

and Pauli operators

$$
\left[\begin{array}{cc}
0 & 1  \tag{8.7}\\
1 & 0
\end{array}\right] \leftrightarrow X, \quad\left[\begin{array}{cc}
1 & 0 \\
0 & -1
\end{array}\right] \leftrightarrow Z .
$$

b) [1 point] Use identities proven in part 1) to express the observable $\mathcal{O}$ in terms of the string order parameters $\mathcal{O}_{1}$ and $\mathcal{O}_{2}$ defined above.
c) [1 point] We now consider the so-called cluster state $|C\rangle$ which is uniquely defined as an eigenstate of so-called stabilizer generators $S_{1}=X_{1} Z_{2}, S_{2}=Z_{1} X_{2} Z_{3}, S_{3}=Z_{2} X_{3} Z_{4}$, and $S_{4}=Z_{3} X_{4}$ with the eigenvalue +1 for all four stabilizer generators. Show that the circuit $U_{\mathrm{CZ}}$


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consisting of CZ gates between neighboring qubits, prepares the cluster state from the product state $|++++\rangle=|+\rangle_{1} \otimes|+\rangle_{2} \otimes|+\rangle_{3} \otimes|+\rangle_{4}$.
d) [1 point] The QCNN output $x_{\mathrm{QCNN}}$ is equal to unity for states belonging to the SPT phase and it is equal to zero for states that do not belong to the SPT phase. Using the equivalence $x_{\mathrm{QCNN}}=\langle\Theta\rangle$, determine whether the cluster state $|C\rangle$ and states $|P\rangle=|++++\rangle$ as well as $|A\rangle=|+-+-\rangle$ belong to the SPT phase.
e) [2 points] An important feature of the QCNN is that it can tolerate certain type of perturbations $\mathscr{P}$ such that a perturbed state $|\tilde{\psi}\rangle=\mathscr{P}|\psi\rangle$ retains the same QCNN output $x_{\mathrm{QCNN}}$ as an unperturbed state $|\psi\rangle$ for any $|\psi\rangle$. Determine, which of the single qubit perturbations

$$
\begin{equation*}
\mathscr{P} \in\left\{X_{1}, X_{2}, X_{3}, X_{4}, Y_{1}, Y_{2}, Y_{3}, Y_{4}, Z_{1}, Z_{2}, Z_{3}, Z_{4}\right\} \tag{8.8}
\end{equation*}
$$

are tolerated by the QCNN, where the matrix representation of the Pauli $Y_{j}$ operator is

$$
Y_{j} \leftrightarrow\left[\begin{array}{cc}
0 & -i  \tag{8.9}\\
i & 0
\end{array}\right]
$$

f) [3 points] Find all states belonging to the SPT phase that yield the QCNN output $x_{Q C N N}=1$.

## Problem 9

## Hawking Radiation, the Logarithmic Phase Singularity, and the Inverted Harmonic Oscillator

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Background A spacetime singularity is located at the center of a black hole and surrounded by an event horizon, separating spacetime into two disjunct regions: one of them accessible to an outside observer and one that is not. At the event horizon, a logarithmic phase singularity emerges in the mode functions of a massless scalar field, being characteristic for Hawking radiation emitted by the black hole.
There are many situations when physical systems display phenomena connected to black hole evaporation. They range from acceleration radiation over the presence of a sonic horizon for sound waves, the quantum catastrophe of slow light and Bose-Einstein condensates, to setups employing water waves. Insight into this plethora of physical systems can be provided by simple models that cover the main features of the underlying effects. In view of Hawking radiation such an elementary model is the inverted harmonic oscillator.

## Overview

In the first part of this exercise, we consider a classical particle of mass $m$ exposed to an inverted harmonic oscillator of steepness $\omega>0$, as described by the potential

$$
\begin{equation*}
V(x)=-\frac{1}{2} m \omega^{2} x^{2} \tag{9.1}
\end{equation*}
$$

which depends on the coordinate $x$ and is depicted in Fig. 9.1. You will show that, similar to the event horizons of a black hole, also an inverted harmonic oscillator displays horizons, which are however located in phase space instead of spacetime.


Figure 9.1 The inverted harmonic oscillator potential $V(x)$, Eq. 9.1, as a function of the position $x$. For each energy $E$ we depict two cases corresponding to an incoming classical particle from the left or right, respectively. A classical particle with negative energy $E<0$ (red and orange lines) is reflected at the potential barrier. On the contrary, a particle with positive energy $E>0$ (blue and green lines) is able to surpass it. Figure reprinted from F. Ullinger et al., AVS Quantum Sci. 4, 024402 (2022) under license CC BY 4.0.

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Next, we turn to the quantum system of an inverted oscillator and analyze its properties. In particular, you will reveal a logarithmic phase singularity in this system and demonstrate that it causes a transmission and reflection coefficient which resembles a very particular quantum statistics.

Afterwards, we identify a logarithmic phase singularity emerging in the mode functions of an electromagnetic field at the event horizon of a black hole. You will show that this particular singularity is a characteristic feature of Hawking radiation.

As a result of your efforts, you will get a glimpse into the intriguing similarities between Hawking radiation emitted at the event horizon of a black hole and the simple system of an inverted harmonic oscillator.
a) $[1.5$ points] First, we consider a one-dimensional inverted harmonic oscillator with steepness $\omega$ as characterized by the potential $V(x)$, Eq. 9.1], displayed in Fig. 9.1. In this system, the dynamics of a classical particle of mass $m$ is governed by the Hamiltonian

$$
\begin{equation*}
H(x, p)=\frac{p^{2}}{2 m}-\frac{1}{2} m \omega^{2} x^{2} \tag{9.2}
\end{equation*}
$$

with position $x$ and momentum $p$. Since the Hamiltonian $H(x, p)$, Eq. (9.2), is time-independent, each classical trajectory is associated with a particular energy $E=H\left(x_{0}, p_{0}\right)$ as determined by the initial conditions $x(0)=x_{0}$ and $p(0)=p_{0}$ for the respective motion at time $t=0$.

1. Identify in a sketch of phase space, i.e. the two-dimensional space of position $x$ and momentum $p$, the regions with phase space trajectories of energy (i) $E<0$, (ii) $E=0$, and (iii) $E>0$.
2. Sketch a phase space trajectory $\{x(t), p(t)\}$ in each quadrant of phase space. How many distinct trajectories exist for a given energy $E$ ?

Hint: In the first task, the relevant quadrants of phase space are identified as regions associated with different energy domains.
b) [1.5 points] In order to make contact with phenomena familiar from black hole evaporation, we introduce the horizon coordinates

$$
\begin{equation*}
\xi \equiv \sqrt{\frac{m \omega}{2 \hbar}}\left(x-\frac{p}{m \omega}\right) \tag{9.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\eta \equiv \sqrt{\frac{m \omega}{2 \hbar}}\left(x+\frac{p}{m \omega}\right), \tag{9.4}
\end{equation*}
$$

where $\hbar$ denotes the reduced Planck constant. We label the coordinates $\xi=0$ and $\eta=0$ as the horizons in phase space. In this particular basis the Hamiltonian H, Eq. (9.2), takes the form

$$
\begin{equation*}
H=-\frac{\hbar \omega}{2}(\xi \eta+\eta \xi) . \tag{9.5}
\end{equation*}
$$

1. Consider a classical particle of mass $m$ in the inverted harmonic oscillator that is initially located at the coordinate $\xi_{0}=\xi(0)$ at time $t=0$. Determine the time $T_{1}$ which the particle requires to arrive at the coordinate $\xi_{1}=\xi\left(T_{1}\right)$ as a function of the initial and final coordinate. For this purpose, solve the equations of motion

$$
\begin{align*}
& \dot{\xi}=\frac{1}{\hbar} \frac{\partial H}{\partial \eta},  \tag{9.6}\\
& \dot{\eta}=-\frac{1}{\hbar} \frac{\partial H}{\partial \xi} . \tag{9.7}
\end{align*}
$$

2. How long does it take for the particle to reach the horizon $\xi=0$ if $\xi_{0} \neq 0$ ? How does your result depend on the value of $\eta_{0}=\eta(0)$ at time $t=0$ ?
3. What happens to the horizons in phase space in the limit $\omega \rightarrow 0$ ? What does this tell you about the allowed values of the energy $E$ in this limit? Support your statements with the help of a phase space sketch.
c) [0.5 points] In the following, we consider a quantum particle of mass $m$ subject to an inverted harmonic oscillator potential $V(x)$, Eq. 9.1). For our analysis, we make use of the operators

$$
\begin{equation*}
\hat{\xi} \equiv \sqrt{\frac{m \omega}{2 \hbar}}\left(\hat{x}-\frac{\hat{p}}{m \omega}\right) \tag{9.8}
\end{equation*}
$$

and

$$
\begin{equation*}
\hat{\eta} \equiv \sqrt{\frac{m \omega}{2 \hbar}}\left(\hat{x}+\frac{\hat{p}}{m \omega}\right), \tag{9.9}
\end{equation*}
$$

defined in terms of the position operator $\hat{x}$ and the momentum operator $\hat{p}$.
Determine the commutator $[\hat{\xi}, \hat{\eta}]$, provided that the position operator $\hat{x}$ and the momentum operator $\hat{p}$ satisfy the standard commutation relation. What does this tell you about the relationship between the operators $\hat{\xi}$ and $\hat{\eta}$ ?
d) [1 point] In analogy to the classical situation, see Eq. (9.5), the quantum mechanical Hamiltonian for an inverted harmonic oscillator takes the form

$$
\begin{equation*}
\hat{H}=-\frac{\hbar \omega}{2}(\hat{\xi} \hat{\eta}+\hat{\eta} \hat{\xi}) \tag{9.10}
\end{equation*}
$$

We are now interested in the energy eigenstates $|\varepsilon\rangle$ of this system which are solutions of the stationary Schrödinger equation

$$
\begin{equation*}
\hat{H}|\varepsilon\rangle=\hbar \omega \varepsilon|\varepsilon\rangle \tag{9.11}
\end{equation*}
$$

with real-valued dimensionless energy $\varepsilon$.
By making use of the $\xi$-representation, show for $\xi \neq 0$ that the two degenerate wave functions

$$
\begin{equation*}
\Psi_{\varepsilon}^{ \pm}(\xi)=\frac{1}{\sqrt{2 \pi|\xi|}} \exp (-\mathrm{i} \varepsilon \ln |\xi|) \Theta( \pm \xi) \tag{9.12}
\end{equation*}
$$

are solutions of Eq. (9.11), which are governed by a logarithmic phase singularity at the horizon $\xi=0$ in phase space. Here we have introduced the Heaviside step function

$$
\Theta(x) \equiv \begin{cases}1, & x \geq 0  \tag{9.13}\\ 0, & x<0\end{cases}
$$

Hint: Analogous to the position representation, the $\xi$-representation $\Psi_{\varepsilon}^{ \pm}(\xi)=\left\langle\xi \mid \Psi_{\varepsilon}^{ \pm}\right\rangle$of a quantum state is defined by making use of the eigenstates $|\xi\rangle$ of the operator $\hat{\xi}$, Eq. (9.8), satisfying the eigenvalue equation $\hat{\xi}|\xi\rangle=\xi|\xi\rangle$.
e) [0.5 points] By solving Eq. (9.11), determine the degenerate eigenstates $\left|\Phi_{\varepsilon}^{ \pm}\right\rangle$with dimensionless energy $\varepsilon$, whose $\eta$-representation $\left\langle\eta \mid \Phi_{\varepsilon}^{ \pm}\right\rangle$is proportional to the Heaviside step function $\Theta( \pm \eta)$.
f) [1.5 points] Show that the quantum state $\left|\Psi_{\varepsilon}^{+}\right\rangle$, see Eq. 9.12), can be expressed as a superposition

$$
\begin{equation*}
\left|\Psi_{\varepsilon}^{+}\right\rangle=S_{+}(\varepsilon)\left|\Phi_{\varepsilon}^{+}\right\rangle+S_{-}(\varepsilon)\left|\Phi_{\varepsilon}^{-}\right\rangle \tag{9.14}
\end{equation*}
$$

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of the states $\left|\Phi_{\varepsilon}^{ \pm}\right\rangle$with energy-dependent coefficients

$$
\begin{equation*}
S_{ \pm}(\varepsilon)=\frac{\Gamma\left(\frac{1}{2}-\mathrm{i} \varepsilon\right)}{\sqrt{2 \pi}} \exp \left[\mp\left(\frac{\mathrm{i} \pi}{4}+\frac{\pi \varepsilon}{2}\right)\right], \tag{9.15}
\end{equation*}
$$

where $\Gamma(z)$ denotes the Euler gamma function.
Hint: Make use of the $\eta$-representation of $\left|\Psi_{\varepsilon}^{+}\right\rangle$and the relation $\langle\eta \mid \xi\rangle=\frac{1}{\sqrt{2 \pi}} \exp (-\mathrm{i} \xi \eta)$ between the states $|\xi\rangle$ and $|\eta\rangle$, which is a consequence of the commutation relation of the respective operators $\hat{\xi}$ and $\hat{\eta}$. Moreover, use the definition of the Euler gamma function $\Gamma(z)=\mathrm{e}^{\mathrm{i} \pi z / 2} \int_{0}^{\infty} \mathrm{d} x x^{z-1} \mathrm{e}^{-\mathrm{i} x}$ with $\Gamma(\bar{z})=\overline{\Gamma(z)}$, where a bar denotes the complex conjugate quantity.
g) $[1.5$ points $]$ Finally, we take a closer look at the probability density $\left|\left\langle\eta \mid \Psi_{\varepsilon}^{+}\right\rangle\right|^{2}$ for the state $\left|\Psi_{\varepsilon}^{+}\right\rangle$:

1. Determine the probability density $\left|\left\langle\eta \mid \Psi_{\varepsilon}^{+}\right\rangle\right|^{2}$ with the help of the corresponding expressions for the weights $\left|S_{ \pm}(\varepsilon)\right|^{2}$.
Hint: Use the relation $\Gamma\left(\frac{1}{2}-\mathrm{i} \varepsilon\right) \Gamma\left(\frac{1}{2}+\mathrm{i} \varepsilon\right)=\pi / \cosh (\pi \varepsilon)$ for the Euler gamma function, where $\cosh (x)=$ $\frac{1}{2}\left(\mathrm{e}^{x}+\mathrm{e}^{-x}\right)$.
2. Indeed, these weights correspond to the transmission $T(\varepsilon)=\left|S_{-}(\varepsilon)\right|^{2}$ and reflection coefficient $R(\varepsilon)=\left|S_{+}(\varepsilon)\right|^{2}$ of the inverted harmonic oscillator. Explain the dependency of these coefficients on the dimensionless energy $\varepsilon$ in comparison to the classical situation with the help of Fig. 9.1 and your phase space sketch of part a) and b).
3. Which particular quantum statistics is resembled by the transmission $T(\varepsilon)$ and reflection coefficient $R(\varepsilon)$ of the inverted harmonic oscillator?
h) [1 point] In the presence of a black hole, the modes of a scalar quantum field $\Psi_{0}(t, r)$ with massand spinless quanta can be determined by the Klein-Gordon equation in curved spacetime. For spherical symmetric waves with vanishing angular momentum, the Klein-Gordon equation takes the form

$$
\begin{equation*}
\left(-\frac{1}{c^{2}} \frac{\partial^{2}}{\partial t^{2}}+\frac{\partial^{2}}{\partial r^{* 2}}\right) r \Psi_{0}=0 \tag{9.16}
\end{equation*}
$$

in the proximity of the black hole. Here $t$ denotes the time and the radius $r>r_{s}$, where the Schwarzschild radius $r_{s}=2 G M / c^{2}$ is governed by the gravitational constant $G$, the speed of light $c$, and the mass $M$ of the black hole. Moreover, we have introduced the Regge-Wheeler tortoise coordinate

$$
\begin{equation*}
r^{*}=r+r_{s} \ln \left|1-\frac{r}{r_{s}}\right| . \tag{9.17}
\end{equation*}
$$

Make use of the separation of variables $\Psi_{0}(t, r)=q(t) R_{0}(r)$ in Eq. 9.16) and determine the ordinary differential equations for the functions $q(t)$ in the temporal domain and $r R_{0}(r)$ in the radial domain. Both equations are connected via the separation constant $\Omega^{2}$, where the frequency $\Omega=c k$ depends linearly on the respective wave number $k$. Determine the two linear independent solutions $R_{0, k}^{ \pm}(r)$ of the radial equation for a fixed value of $k$ and show that these modes contain a logarithmic singularity that emerges at the event horizon of the black hole located at $r=r_{s}$.
i) [1 point $]$ Central to the emission of Hawking radiation at the event horizon of a black hole is the expansion of a plane wave of frequency $\omega$ in the Kruskal-Szekeres coordinates $u$ and $v$, in terms of modes of frequency $\Omega$ that display a logarithmic singularity at the event horizon $r=r_{s}$ and are associated with the Schwarzschild coordinates $t$ and $r^{*}$. In particular, there exists the decomposition

$$
\begin{equation*}
\frac{1}{\sqrt{\omega}} \mathrm{e}^{-\mathrm{i} \omega u}=\int_{0}^{\infty} \frac{\mathrm{d} \Omega^{\prime}}{\sqrt{\Omega^{\prime}}}\left(\alpha_{\Omega^{\prime} \omega} \mathrm{e}^{-\mathrm{i} \Omega^{\prime} \tilde{u}}+\bar{\beta}_{\Omega^{\prime} \omega} \mathrm{e}^{\mathrm{i} \Omega^{\prime} \tilde{u}}\right) \tag{9.18}
\end{equation*}
$$

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with expansion coefficients $\alpha_{\Omega^{\prime} \omega}$ and $\beta_{\Omega^{\prime} \omega}$, where $\tilde{u}=t-r^{*}$. Moreover, $\bar{\beta}_{\Omega^{\prime} \omega}$ denotes the complex conjugate of $\beta_{\Omega^{\prime} \omega}$. Here and in the following we make use of the convention $c=1$.

1. Show that the expansion coefficient $\beta_{\Omega \omega}$ in Eq. 9.18) can be expressed as

$$
\begin{equation*}
\beta_{\Omega \omega}=\frac{1}{2 \pi} \sqrt{\frac{\Omega}{\omega}} \int_{-\infty}^{\infty} \mathrm{d} \tilde{u} \mathrm{e}^{\mathrm{i} \omega u+\mathrm{i} \Omega \tilde{u}} \tag{9.19}
\end{equation*}
$$

Evaluate the integral in Eq. 9.19 for $\Omega>0$ by using the relation $\tilde{u}=-2 r_{s} \ln \left(-\frac{u}{2 r_{s}}\right)$.
Hint: Apply the definition $\delta(x)=\frac{1}{2 \pi} \int_{-\infty}^{\infty} \mathrm{d} y \mathrm{e}^{\mathrm{i} x y}$ of the Dirac delta function and recall the definition of the Euler gamma function $\Gamma(z)$ provided in part $f$ ).
2. With the help of Eq. (9.19), the mean number of particles emitted by the black hole as Hawking radition in the mode with frequency $\Omega$ reads

$$
\begin{equation*}
N_{\Omega}=\int_{0}^{\infty} \mathrm{d} \omega\left|\beta_{\Omega \omega}\right|^{2}=n(\Omega) \int_{0}^{\infty} \frac{\mathrm{d} \omega}{2 \pi \kappa \omega} . \tag{9.20}
\end{equation*}
$$

Determine the function $n(\Omega)$ in Eq. 9.20 by using the surface gravity $\kappa=1 /\left(2 r_{s}\right)$ of the black hole as a parameter. Compare this result to the one obtained in part g) for the inverted harmonic oscillator.
Hint: Apply the identity $\Gamma(-\mathrm{i} z) \Gamma(\mathrm{i} z)=\pi /[z \sinh (\pi z)]$ for the Euler gamma function, where $\sinh (\pi z)=$ $\frac{1}{2}\left(\mathrm{e}^{\pi z}-\mathrm{e}^{-\pi z}\right)$.

In the end, we want to emphasize that a rigorous treatment of the emission of Hawking radiation at the event horizon of a black hole is only possible within second quantization. However, this exercise gives you some insight into the crucial role of the logarithmic phase singularity for the occurrence of this fascinating phenomenon. Moreover, it reveals the astonishing similarities to the simple quantum system of an inverted harmonic oscillator.

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## Problem 10

## Rare and Extreme Events in Nonlinear Physics: From Fiber Optics to Oceanic Waves

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Background Single mode optical fibers are a nearly ideal medium of propagation: the very low level of attenuation of silica combined with the single mode behavior of the fiber enables light to propagate with a spatial profile unaffected over kilometers and kilometers. However, in the case of ultrashort and powerful pulses, two effects have to be taken into account: the dispersion and the nonlinearity that are related to the dependence of the optical index on the frequency and power, respectively.

In the present exercise, we explore the intriguing relationship between the propagation of light in single mode optical fibers and the occurrence of rare and extreme events for oceanic waves.

In the first part of the exercise, we compare the propagation of ultrashort optical pulses and the spatial profile of continuous electromagnetic waves. For an ultrashort optical pulse we display in Fig. 10.1 (a) the intensity of the electromagnetic field including the optical carrier (blue) and the temporal profile of the slowly-varying envelope $|\psi(z, t)|^{2}$ (red) at a given position $z=z_{0}$. In Fig. 10.1 (b) we show the spatial intensity distribution $|\Psi(z, x)|^{2}$ of a continuous electromagnetic wave as a function of the propagation coordinate $z$ and the transversal coordinate $x$.


Figure 10.1 (a) The temporal intensity profile of an ultrashort optical pulse (blue) and its envelope $|\psi(z, t)|^{2}$ (red) at a given position $z=z_{0}$. (b) The spatial intensity profile $|\Psi(z, x)|^{2}$ of a continuous electromagnetic wave with regard to the transversal coordinate $x$ and the propagation coordinate $z$.
a) $[0.5$ points $]$ We study the dynamics of an ultrashort pulse with duration above 1 ps as depicted in Fig. 10.1 (a). Under the approximation of a slowly-varing envelope (i.e. the optical carrier of the light pulse is neglected) and within the scalar approximation, the evolution of the complex electric field $\psi(z, t)$ is governed by the partial differential equation

$$
\begin{equation*}
\mathrm{i} \frac{\partial \psi}{\partial z}=\frac{\beta_{2}}{2} \frac{\partial^{2} \psi}{\partial t^{2}} \tag{10.1}
\end{equation*}
$$

with $z$ and $t$ being the distance and temporal coordinate, respectively. Here $\beta_{2}$ denotes the secondorder dispersion coefficient. At the position $z=z_{0}$, the shape of the pulse is determined by the initial condition $\psi\left(z_{0}, t\right)=\psi_{0}(t)$.

In order to understand the effect of dispersion, it is beneficial to work in Fourier space. The Fourier transform of $\psi(z, t)$ is given by

$$
\begin{equation*}
\tilde{\psi}(z, \omega)=\frac{1}{\sqrt{2 \pi}} \int \mathrm{~d} t \mathrm{e}^{\mathrm{j} \omega t} \psi(z, t) . \tag{10.2}
\end{equation*}
$$

Using Eq. 10.1) please derive a solution for $\tilde{\psi}(z, \omega)$ and explain the effect of dispersion with it.
b) $[0.5$ points $]$ We turn now to the spatial propagation of the complex electric field $\Psi(x, z)$ of a continuous wave as displayed in Fig. 10.1(b). The Helmholtz equation that rules diffraction under 1D paraxial conditions reads

$$
\begin{equation*}
\mathrm{i} \frac{\partial \Psi}{\partial z}=-\frac{\lambda}{4 \pi} \frac{\partial^{2} \Psi}{\partial x^{2}} \tag{10.3}
\end{equation*}
$$

with $z$ and $x$ being the longitudinal and transverse coordinate, respectively. Here $\lambda$ denotes the wavelength and $\Psi_{0}(x)=\Psi\left(z_{0}, x\right)$ is the initial profile at $z=z_{0}$.

What are the analogies that can be drawn between the dispersion of an ultrashort pulse and the diffraction of a continuous wave? Comment on the impact of dispersion and diffraction.

Hint: Make use of Fourier space for your analysis.
c) [0.5 points] Next, we analyze the dynamics of an ultrashort optical pulse $\psi(z, t)$ for a negligible second-order dispersion coefficient $\left|\beta_{2}\right| \ll 1$ in Eq. 10.1). When the effects of nonlinearity in the optical fibre become significant, the electromagnetic field evolves according to the equation

$$
\begin{equation*}
\frac{\partial \psi}{\partial z}=\mathrm{i} \gamma|\psi|^{2} \psi \tag{10.4}
\end{equation*}
$$

where $\gamma$ is the nonlinear coefficient of the optical fiber.
Consider the case that the intensity profile $|\psi(z, t)|^{2}$ is independent of the distance $z$ and determine the corresponding solution of Eq. (10.4). What is the physical consequence of the so-called Kerr nonlinearity in Eq. (10.4) on the temporal profile of the pulse?
d) [1 point] For an ultrashort optical pulse in a nonlinear fiber, an effect called self-focusing can occur. To obtain a deeper insight into this phenomenon, we establish again an analogy to the spatial profile $\Psi(z, x)$ of a continuous electromagnetic wave. In wave optics, the impact of a perfectly converging 1D lens of focal length $f$ situated at the propagation coordinate $z=z_{1}$ can be described as

$$
\begin{equation*}
\Psi\left(z_{1}^{+}, x\right)=\exp \left(-\mathrm{i} \frac{\pi x^{2}}{\lambda f}\right) \Psi\left(z_{1}^{-}, x\right), \tag{10.5}
\end{equation*}
$$

where $\Psi\left(z_{1}^{-}, x\right)$ and $\Psi\left(z_{1}^{+}, x\right)$ are the fields directly before and after the lens. Here $\lambda$ is the wavelength introduced in Eq. 10.3).

Explain why the nonlinearity in Eq. (10.4) acts like a converging lens. For this purpose, we analyze an ultrashort optical pulse with a symmetric temporal profile $\psi\left(z_{0}, t\right)$ at $z=z_{0}$. As an example please use a Gaussian pulse $\psi(z, t)=\psi_{\max } \mathrm{e}^{-\frac{t^{2}}{K^{2}}}$, with temporal width $K$ and amplitude $\psi_{\max }$. For this exercise it is sufficient to approximate the pulse shape to second-order in $t$. Note, that the intensity profile $|\psi(z, t)|^{2}$ remains independent of $z$ as in $\left.\mathbf{c}\right)$. Determine the waveform $\psi(z=d, t)$ at the position $z=d>z_{0}$ and compare it to Eq. 10.5).

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In the second part of the exercise, we take a closer look at nonlinear effects. Indeed, for ultrashort high-power waveforms, both dispersive and nonlinear effects act simultaneously. Thus, the evolution of the optical pulse is described by the nonlinear Schrödinger equation

$$
\begin{equation*}
\mathrm{i} \frac{\partial \psi}{\partial z}=\frac{\beta_{2}}{2} \frac{\partial^{2} \psi}{\partial t^{2}}-\gamma|\psi|^{2} \psi \tag{10.6}
\end{equation*}
$$

By using the normalized coordinates $\xi=z / L$ and $\tau=t / t_{0}$ with the characteristic length $L=$ $1 /\left(\gamma P_{0}\right)$ and time $t_{0}=\sqrt{\left|\beta_{2}\right| L}$, Eq. (10.6) reduces for $\beta_{2}<0$ to

$$
\begin{equation*}
\mathrm{i} \frac{\partial A}{\partial \xi}=-\frac{1}{2} \frac{\partial^{2} A}{\partial \tau^{2}}-|A|^{2} A \tag{10.7}
\end{equation*}
$$

where the function $A=\psi / \sqrt{P_{0}}$ contains the typical power $P_{0}$ of the waveform under study.
e) [2 points] The mathematical solutions of the nonlinear Eq. (10.7) are non-trivial. However, some specific wave forms have been identified in the past. We focus our attention on two of these waves, the soliton

$$
\begin{equation*}
A_{s}(\xi, \tau)=\operatorname{sech}(\tau) \mathrm{e}^{\mathrm{i} \xi / 2} \tag{10.8}
\end{equation*}
$$

and the Peregrine breather

$$
\begin{equation*}
A_{p}(\xi, \tau)=\left[1-\frac{4(1+2 \mathrm{i} \xi)}{1+4 \tau^{2}+4 \xi^{2}}\right] \mathrm{e}^{\mathrm{i} \xi} . \tag{10.9}
\end{equation*}
$$

Here we have introduced the hyperbolic secant function

$$
\begin{equation*}
\operatorname{sech}(\tau)=\frac{2}{\mathrm{e}^{\tau}+\mathrm{e}^{-\tau}} \tag{10.10}
\end{equation*}
$$

Plot the very approximate intensity profiles $\left|A_{s}\right|^{2}$ and $\left|A_{p}\right|^{2}$ at $\xi=0, \xi=-\infty$ and $\xi=\infty$ as a function of $\tau$. Identify in both cases the value of the intensity at $\tau= \pm \infty$ as well as the peak power at $\tau=0$. How does the peak power of the two waves evolve as a function of $\xi$ ? Identify the main differences between these two waves.

Hint: For the soliton case, you may find insights by using a rough approximation of the exponential to the second-order; qualitative links to a Lorentzian waveform can also be drawn.
f) [1 point $]$ All the effects observed in e) are intimately linked to a process that is called modulation instability. In order to highlight this phenomenon, let us switch again to the unnormalized Schrödinger equation (10.6) and consider a continuous wave

$$
\begin{equation*}
\psi_{C}(z, t)=\psi_{0} \exp \left(\mathrm{i} \gamma P_{0} z\right) \tag{10.11}
\end{equation*}
$$

which is a solution of equation 10.6 . Here $\psi_{0}$ and $P_{0}$ are real-valued and correspond to the initial wave amplitude and power, respectively. In order to check if the solution $\psi_{C}(z, t)$, Eq. 10.11 , is stable against perturbation, we consider the perturbed wave

$$
\begin{equation*}
\psi_{\varepsilon}(z, t)=\left[\psi_{0}+\varepsilon(z, t)\right] \exp \left(\mathrm{i} \gamma P_{0} z\right)=\psi_{C}+\varepsilon(z, t) \exp \left(\mathrm{i} \gamma P_{0} z\right) . \tag{10.12}
\end{equation*}
$$

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By plugging the perturbed wave $\psi_{\varepsilon}(z, t)$ into the nonlinear Schrödinger equation 10.6 , derive the equation

$$
\begin{equation*}
\mathrm{i} \frac{\partial \varepsilon}{\partial z}=\frac{\beta_{2}}{2} \frac{\partial^{2} \varepsilon}{\partial t^{2}}-\gamma P_{0}\left(\varepsilon+\varepsilon^{*}\right) \tag{10.13}
\end{equation*}
$$

that is satisfied by the function $\varepsilon(z, t)$.
Hint: The perturbation is assumed to be small, so that terms of order $\varepsilon^{2}$ can be neglected.
g) [2 points] We are looking for a solution of Eq. 10.13 ) that can be expressed as a plane wave

$$
\begin{equation*}
\varepsilon(z, t)=a_{1} \exp [\mathrm{i}(k z-\omega t)]+a_{2} \exp \left[-\mathrm{i}\left(k^{*} z-\omega t\right)\right] \tag{10.14}
\end{equation*}
$$

where $a_{1}, a_{2}$, and $k$ are complex-valued constants. Show that $a_{1}$ and $a_{2}$ are solutions of the system

$$
\begin{align*}
& \left(\frac{\beta_{2}}{2} \omega^{2}+\gamma P_{0}-k\right) a_{1}+\gamma P_{0} a_{2}^{*}=0 \\
& \gamma P_{0} a_{1}^{*}+\left(\frac{\beta}{2} \omega^{2}+\gamma P_{0}+k^{*}\right) a_{2}=0 \tag{10.15}
\end{align*}
$$

of coupled equations. For certain $k$ these coupled equations can have non-trivial solutions. Determine $k$ for a non-trivial solution as a function of the parameters $\beta_{2}, \omega, \gamma$, and $P_{0}$.
h) [1.5 points] The nonlinear system will be stable against perturbation when $k$ is purely real. Otherwise, when $k$ contains an imaginary part, an exponential growth of the perturbation will happen as evident from Eq. 10.14 ). Can the propagation be unstable in the regime of normal dispersion $\left(\beta_{2}>0\right)$ or anormalous dispersion $\left(\beta_{2}<0\right)$ ? Derive the range of the frequency $\omega$ for which the wave is unstable. What is the frequency for which most of the gain is observed (the gain is given by the imaginary part of $k$ ). Draw the approximate shape of the gain as a function of the frequency $\omega$.
i) [1 point] The nonlinear Schrödinger equation also models the propagation of oceanic waves. In this context, the envelope $u(z, t)$ of a modulated wave train with wave vector $k_{0}$ propagating in a 1D water tank along the $z$-direction is governed by the equation

$$
\begin{equation*}
\mathrm{i} \frac{\partial u}{\partial z}=\frac{1}{g} \frac{\partial^{2} u}{\partial t^{2}}+k_{0}^{3}|u|^{2} u \tag{10.16}
\end{equation*}
$$

with $g$ being the gravitational acceleration. By using normalized quantities, Eq. 10.16 can be cast into the form

$$
\begin{equation*}
\mathrm{i} \frac{\partial U}{\partial \xi}=-\frac{1}{2} \frac{\partial^{2} U}{\partial \tau^{2}}-|U|^{2} U \tag{10.17}
\end{equation*}
$$

Propose a solution $U(\xi, \tau)$ of Eq. 10.17) that could be relevant for the explanation of oceanic rogue waves. These are particular waves that appear from nowhere and disappear without leaving a trace.

